Figure 2 shows $E_{\Delta}(\mathbf{q})$ for a succession of times Δ from 20 to 110 ms. From the low-q data, we find $D_{\rm eff} = 2 \times 10^{-9} \, \rm m^2 \, s^{-1}$, so the timescale ranges from $0.3(b^2/2D_{\rm eff})$ to $1.8(b^2/2D_{\rm eff})$. A coherence peak at $q \approx (16 \,\mu{\rm m})^{-1}$ is clearly visible at values of Δ sufficiently large (≥70 ms) for the molecules to diffuse from the starting pore to a first neighbour.

A quantitative fit to the data is possible using equation (3). A simple approximation to $C(Z, \Delta)$ is to assume a gaussian envelope⁶, but a more precise description can be made if we consider the cumulative effects or successive pore hops. This pore-hopping formalism yields an approximate closed-form expression for $E_{\Delta}(q)$ in the case of the pore glass, namely

$$E_{\Delta}(q) = |S_0(q)|^2 \times \exp\left[-\frac{6D_{\text{eff}}\Delta}{b^2 + 3\xi^2} \left(1 - \exp\left(-2\pi^2 q^2 \xi^2\right) \frac{\sin(2\pi qb)}{2\pi qb}\right)\right]$$
(4)

where b is the mean and \mathcal{E} the standard deviation of the distance from the starting pore to the nearest-neighbour pore shell. A more detailed description of pore-hopping theory will be published elsewhere. Figure 3 shows the data for $\Delta = 70$ ms, together with a theoretical curve obtained by using equation (4) in a nonlinear least-squares fit. For simplicity, the form factor chosen corresponds to a spherical pore of diameter a and is thus rather unrealistic. Nonetheless, the fit is fairly good and yields structural parameters $b = 16.1 \,\mu\text{m}$, $a = 5.6 \,\mu\text{m}$ and $\xi = 2.85 \,\mu\text{m}$, which correspond to the physical dimensions of the packed

We have performed an inverse Fourier transformation on the $\Delta = 110$ -ms data of Fig. 2, using three-dimensional projection reconstruction and assuming the system to be isotropic. This gives an 'image' of the spherically averaged autocorrelation function for the pores convoluted with the diffusion-weighted three-dimensional lattice correlation function (as opposed to the projection, L(Z), of this function along a single axis). Figure 4 shows a slice through the centre of this three-dimensional 'image'.

For the q-space imaging of dynamic displacements, the entire sample contributes to the 'image' signal-to-noise ratio; the resol-

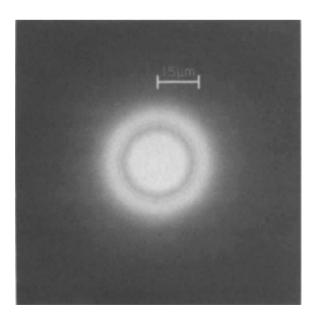


FIG. 4 'Image' of the pore autocorrelation function convoluted with the diffusion-weighted three-dimensional lattice correlation function. The 'image' was obtained by Fourier transformation of the 110-ms data of Fig. 2. The bright inner circle and the first bright ring correspond to the starting pores and the first-neighbour pore shells of the 16-µm spheres respectively.

ution is limited only by the available magnitude of q. This is in contrast to NMR imaging in k-space, where increasing the resolution by increasing the imaging gradient results in a deteriorating signal-to-noise ratio in each volume element of the 'image'. We envisage that q-space imaging could realistically achieve sub-micrometre resolution.

The observation of a coherence peak as the gradient is increased in a PGSE experiment is remarkable and completely contrary to the usual expectation of monotonically decreasing $E_{\Delta}(\mathbf{q})$ with increasing \mathbf{q} . Such a peak arises because of structural features in the porous solid. A significant number of molecules moving one pore spacing suffer no net phase shift when $qb \approx 1$. We are unaware of any previous measurement in which $E_{\Lambda}(\mathbf{q})$ increases with increasing q.

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Air entrainment and dissipation in breaking waves

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WAVE breaking transfers momentum from the atmosphere (winds) to the ocean (currents)^{1,2} and entrains air in bubbles which are believed to generate and scatter underwater sound³⁻⁵. Wave breaking and the associated entrainment of air in bubbles are also thought to be important in heat and gas transfer across the air-sea interface⁶⁻⁸, but the lack of detailed measurements of air entrainment in bubbles has impeded our understanding of the effect of wave breaking on these processes. Here we present measurements of air entrainment by controlled deep-water breaking waves, which show that the bubble plumes generated by breaking waves contain volume fractions of air that are many orders of magnitude greater than expected. Bubble plumes with such large void fractions may be the source of low-frequency sound in the ocean⁹. We conclude that the processes of surface-wave evolution and air entrainment are dynamically coupled, and that the contribution of bubbles to air-sea gas transfer and to sound propagation may be seriously underestimated if the existence of these plumes of large bubbles is not taken into account.

Experiments were conducted in a wave channel 25-m long and 0.7-m wide filled with fresh water to a depth of 0.6 m. The experiment consisted of generating breaking waves and mapping the bubble plume created by breaking for three different amplitudes of the same wave packet (see Table 1 for wave-packet characteristics). The breaking waves were produced by a pistontype wavemaker. Details of wave generation and photographs of breaking waves are given by Rapp and Melville². The technique gives very repeatable wave profiles and energy dissipation, and we found it to give fairly repeatable bubble plumes. The volume fraction of air (void fraction, given in % hereafter) in an air-water mixture can be measured by making use of the large difference in electrical conductivity between air and water. This technique has been used in closed-conduit two-phase flows, and reviews can be found in the literature^{10,11}. We used essentially the same technique to map the void-fraction distribution in bubble plumes generated by breaking waves. Typical wavegauge and void-fraction time series are shown in Fig. 1. Additional details of the probe and the experimental procedures will be published elsewhere.

Contour maps showing the evolution of the void-fraction distribution can be assembled from the individual time series (Fig. 2). Measurements over the full range 0-100% of void fractions have been observed, and void fractions of >20% for all three wave amplitudes were sustained for up to half a wave period after breaking. These measurements show that the volume fractions of air near the surface within one wave period following breaking are many orders of magnitude greater than the time-averaged (over $\sim 10 \text{ min}$) values measured in the field¹². It is well known that the speed of sound in water can be reduced by an order of magnitude in the presence of void fractions as low as 1%. Our results therefore suggest caution in using time-averaged void-fraction measurements to infer sound propagation through the surface bubble layer (which acts as an acoustic waveguide¹³).

The important parameters describing the bubble plume are presented in Fig. 3. The total volume of entrained air, V, shown in Fig. 3a is computed from

$$V = b \int_{A} \alpha \, dA \tag{1}$$

where α is the local void fraction, b is the channel width and A is the cross-sectional area of the bubble plume. The volume of air enclosed in the initial air pocket is conserved for up to a quarter of a wave period after breaking. Degassing of the plume is very rapid, with only 5% of the initially entrained air remaining after a full wave period. The fast rising speed of large bubbles (radius > 1 mm) must account for most of the air lost in the first wave period. Laboratory wind-flume experiments¹⁴ have shown the contribution to total flux of carbon dioxide by bubbles to be almost independent of radius in the range 0.02-2 mm despite the fact that larger bubbles are less numerous and have a shorter underwater residence time. The very fast degassing rate of the bubble plume revealed by our experiments indicates that modelling of the contribution of bubbles to total air-sea gas transfer may be considerably underestimated if the transient large bubble population (radius $\sim 1-10$ mm) is not considered.

The cross-sectional area of the bubble plume is shown in Fig. 3b. The void-fraction gauge used in our experiments is insensitive

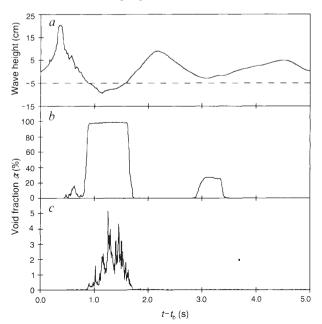


TABLE 1 Characteristics of the three wave amplitudes studied.

ak	t _b (s)	<i>x</i> _b (m)	$E_{\rm w}/{\rm b}$ (J m ⁻¹)	E_{d}/b (J m ⁻¹)	V _o (cm ³)	$E_{\rm d}/\rho g V_{\rm O} \lambda$		Δz (cm)
0.54	14.4	8.05	110.0	17.8	6,860	0.10	5	5
0.45	14.3	7.70	78.0	8.6	3,220	0.10	5	5
0.38	14.3	7.70	58.7	4.3	1,750	0.09	5	5

The slope of the packet² is given by ak. The centre frequency of the wave packet and the bandwidth were both 0.88 Hz. The time from initial motion of the piston is $t_{\rm b}$, and $x_{\rm b}$ is the breaking location downstream of the piston. Both $t_{\rm b}$ and $x_{\rm b}$ are defined by the time at which the forward-moving jet strikes the free surface and an air pocket is formed. The volume of the air pocket at $t=t_{\rm b}^+$ is $V_{\rm O}$ (measured from video images at $t_{\rm b}$; because of lack of video resolution for ak = 0.38, $V_{\rm O}$ was taken as the maximum V measured). $E_{\rm w}$ is the total pre-breaking wave energy, $E_{\rm d}$ the total energy dissipated by breaking². $E_{\rm d}/\rho g V_{\rm O} \lambda$ is the ratio of wave energy dissipated to the maximum volume of air entrained normalized by the specific weight of water ρg and the characteristic wavelength λ . The horizontal and vertical resolutions of the void-fraction measurements are Δx and Δz . The channel width, water density and gravity are b,ρ and g.

to void fractions lower than 0.3%. We expect the initial rise in bubble-plume area to be essentially independent of the void-fraction detection threshold, giving an area expansion rate of $28\,V_0/bT$ (where T is the characteristic wave period) for the time between 0.1 to 0.3T. We expect that the rate of decrease of A would be lower in the later stages (after the peak value) if a lower threshold were attainable with the instrument.

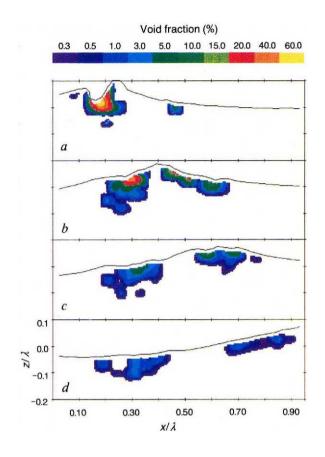
The mean void fraction is given by $\bar{\alpha} = V/bA$ (Fig. 3c). Mean void fractions in the bubble plume remain above 1% within the first wave period after breaking. Important changes in the speed of sound are associated with these localized distributions of large void fractions. Such discontinuities have been suggested previously as a possible source of low-frequency sound (<1 kHz) in the ocean¹⁵. Our results indicate that these large discontinuities exist in the laboratory and are likely to be found in the field.

The work required to keep the air entrained against the buoyancy force is

$$E_{\rm b} = \rho g b \int_{A} \alpha z \, dA \tag{2}$$

where ρ is the water density, g is the acceleration due to gravity and z is the vertical distance to the free surface. Normalizing

FIG. 1 Typical time series at 200 Hz of a, wave-gauge measurements; b, c, void-fraction measurements at depths $-5\,\mathrm{cm}$ and $-15\,\mathrm{cm}$, respectively, from the still-water level. All data are for the most energetic breaker studied at $0.55\,\mathrm{m}$ downstream of x_b . Note how the probe crosses the water surface at $0.8\,\mathrm{s}$ in b. 'Surface effect' is shown in b at $3\,\mathrm{s}$. The second wave trough has its water surface at $\sim -2.5\,\mathrm{cm}$ and therefore intrudes into the measuring volume of the void-fraction gauge which is located at $-5\pm3\,\mathrm{cm}$. The effective measuring volume of the probe was a horizontal cylinder $\sim\!20\,\mathrm{cm}$ long and $\sim\!6\,\mathrm{cm}$ in diameter.



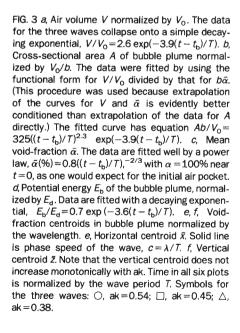
the data by the total wave energy dissipated by breaking, $E_{\rm d}$, gives a simple exponential form (Fig. 3d). Up to 40% of the total prebreaking wave energy can be lost through breaking¹; our data now show that a large fraction (30-50% and maybe more) of the energy lost is expended in entraining the bubble plume. This is direct evidence that the processes of surface wave evolution and air entrainment have considerable dynamical coupling. The near-constant ratio $E_{\rm d}/\rho g V_0 \lambda$ for these experiments, as shown in Table 1, implies that the initial volume of air entrained correlates with the energy dissipated. Recent studies 16,17 have shown that the wave energy dissipated correlates with the acoustic energy radiated and the backscattering of microwave by radar breaking waves. Thus our measurements suggest that it may be possible to quantify air entrainment and gas transfer in the field using acoustic and microwave techniques.

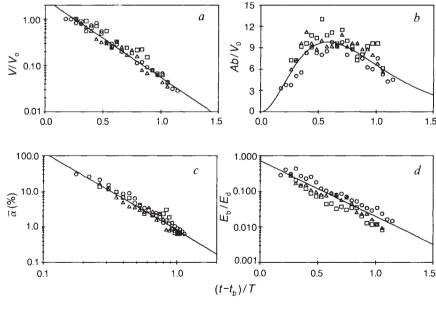
The horizontal and vertical centroids of the void-fraction distribution in the bubble plume \bar{x} and \bar{z} , respectively, are

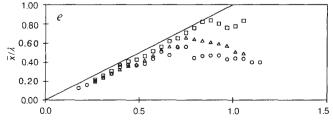
$$(\bar{x}, \bar{z}) = \frac{\int_A \alpha(x, z) \, dA}{\int_A \alpha \, dA}$$
 (3)

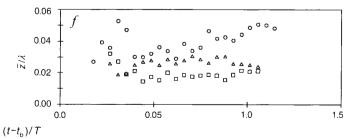
where x is the horizontal distance from x_b and z is the depth from the free surface. The horizontal centroid in Fig. 3e moves at roughly the phase speed of the wave for a period T/2. In field studies⁵ using sonar, it was found that the cloud in the

FIG. 2 Contour maps of void fractions for the most energetic breaker studied. Time increases from a to d. Times from breaking, $t-t_{\rm b}$, are 0.3, 0.5, 0.7 and 1.0 s; times normalized by the wave period, $(t-t_{\rm b})/T$, are 0.26, 0.44, 0.62 and 0.88 respectively. The wave moves from left to right. Each frame is constructed from \sim 170 ensemble averages of three runs. Note the distinct downstream cloud generated by the splash from the initial impact at breaking.









early stage after breaking moved at the wind-wave phase speed. The above results are consistent with these findings. The vertical centroid for each packet shown in Fig. 3f is roughly constant, but values for different packets range between 0.015λ and 0.05λ where λ is a characteristic wavelength. This suggests that, at least in the first wave period, the downward advection of fluid may balance the upward motion of the bubbles themselves.

We have shown that the bulk properties of the bubble plume generated by breaking waves scale with the prebreaking wave variables and evolve according to simple functions of time. The close dynamical coupling between wave breaking and air entrainment suggests that models of air-sea gas transfer could be improved by better characterization of breaking surface waves, perhaps through remote sensing methods¹⁷.

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Constraints from noble-gas contents on the origin of carbonado diamonds

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CARBONADOS are porous aggregates of micrometre-size diamond crystals^{1,2}. Although they are not rare, they have not been found in kimberlites³, and they contain inclusion minerals typical of the Earth's crust, rather than the upper-mantle assemblages commonly found in kimberlite diamonds. Carbonados also have lower 13C/12C ratios than kimberlite diamonds 1,2,4. Although these observations strongly suggest that carbonados were formed in the crust, crustal conditions are generally unlikely to provide pressures and temperatures in the diamond stability field (but see ref. 5 for a possible exception). Other suggestions for the origin of carbonado include the transformation of subducted carbon in the mantle⁶, impact metamorphism of crustal rocks containing organic carbon⁷, and (for very fine-grained carbonado) the irradiation of organic matter by decaying uranium and thorium in uranium-rich phases⁸⁻¹⁰. Here we present further evidence for a crustal connection, in the form of noble-gas data for four carbonados from Brazil and Africa.

We find that all four contain large amounts of implanted xenon and krypton from ²³⁸U fission, nucleogenic neon and ⁴He, and tightly trapped atmospheric noble gases, from which we conclude that these carbonados formed in a uranium-rich crustal environment.

We studied two carbonados from Brazil and two from Africa, all from different localities. Before the noble gas experiments. samples were thoroughly cleaned with hot HNO₃ and HF. Noble gases were extracted by heating the samples at temperatures up to 2,000 °C (graphitization temperature is 1,900 °C) and analysed by mass spectrometry. Table 1 gives the analytical data and details of the method. The isotopic compositions of neon, krypton and xenon are distinctly different from those in the atmosphere. The extraordinary neon isotope ratios can be attributed to nuclear reactions (Wetherill reactions)11 such as 18O to nuclear reactions (wetneriti reactions) such as 10 C (α , n) 21 Ne and 19 F (α , n) 22 Ne. Assuming that 130 Xe, 80 Kr and 20 Ne are entirely atmospheric, we calculated the excess of the isotopes 136 Xe, 86 Kr and 21 Ne in the samples relative to the values expected if the ratios were atmospheric. We show these in Table 2 together with their uranium and ⁴He contents, and δ^{13} C values. The excess Xe and Kr isotopes must arise from fission of ²³⁸U, and are given the subscript 'fission' in the table. In Fig. 1, we plot ¹³⁶Xe/¹³²Xe against ¹³⁴Xe/¹³²Xe obtained when the African sample 90706P was degassed by step-heating: the data show that Xe in the diamond is a mixture of atmospheric Xe and Xe arising from ²³⁸U fission. Published values ¹² of the production ratios for ⁴He/¹³⁶Xe and ¹³⁶Xe/⁸⁶Kr in spontaneous fission of 238 U are 0.3×10^9 and 6.0 respectively. These are well within the range for the observed ratios of $0.27-0.8\times10^9$ and 3.8-12.6. Table 2 also shows the amounts of nucleogenic ¹³⁶Xe,

